nag_hermitian_lin_eqn_mult_rhs (f04awc)

1. Purpose

nag_hermitian_lin_eqn_mult_rhs (f04awc) calculates the approximate solution of a set of complex Hermitian positive-definite linear equations with multiple right-hand sides, $AX = B$, where A has been factorized by nag_complex_cholesky (f01bnc).

2. Specification

```
#include <nag.h>
#include <nagf04.h>

void nag_hermitian_lin_eqn_mult_rhs(Integer n, Integer nrhs, Complex a[],
    Integer tda, double p[], Complex b[], Integer tdb, Complex x[],
    Integer tdx, NagError *fail)
```

3. Description

To solve a set of complex linear equations, $AX = B$, where A is positive-definite Hermitian, this routine must be preceded by a call to nag_complex_cholesky (f01bnc) which computes a Cholesky factorization $A = U^H U$, where U is an upper triangular matrix with real diagonal elements. The columns x of the solution X are found in two steps $U^H y = b$ and $Ux = y$, where b is a column of the right-hand side matrix B.

4. Parameters

n

　　Input: n, the order of the matrix A.
　　Constraint: **n** ≥ 1.

nrhs

　　Input: r, the number of right-hand sides.
　　Constraint: **nrhs** ≥ 1.

a[n][tda]

　　Input: the off-diagonal elements of the upper triangular matrix U as returned by nag_complex_cholesky (f01bnc). The lower triangle of the array is not used.

tda

　　Input: the second dimension of the array **a** as declared in the function from which nag_hermitian_lin_eqn_mult_rhs is called.
　　Constraint: **tda** $\geq$ **n**.

p[n]

　　Input: the reciprocals of the diagonal elements of U, as returned by nag_complex_cholesky (f01bnc).

b[n][tdb]

　　Input: the n by r right-hand side matrix B. See also Section 6.

tdb

　　Input: the second dimension of the array **b** as declared in the function from which nag_hermitian_lin_eqn_mult_rhs is called.
　　Constraint: **tdb** $\geq$ **nrhs**.

x[n][tdx]

　　Output: the n by r solution matrix X. See also Section 6.

tdx

　　Input: the second dimension of the array **x** as declared in the function from which nag_hermitian_lin_eqn_mult_rhs is called.
　　Constraint: **tdx** $\geq$ **nrhs**.

> **fail**
>> The NAG error parameter, see the Essential Introduction to the NAG C Library.

5.   Error Indications and Warnings

> **NE_INT_ARG_LT**
>> On entry, **nrhs** must not be less than 1: **nrhs** = $\langle value \rangle$.
>> On entry, **n** must not be less than 1: **n** = $\langle value \rangle$.

> **NE_2_INT_ARG_LT**
>> On entry, **tda** = $\langle value \rangle$ while **n** = $\langle value \rangle$. These paremters must satisfy **tda** $\geq$ **n**.
>> On entry, **tdb** = $\langle value \rangle$ while **nrhs** = $\langle value \rangle$. These parameters must satisfy **tdb** $\geq$ **nrhs**.
>> On entry, **tdx** = $\langle value \rangle$ while **nrhs** = $\langle value \rangle$. These parameters must satisfy **tdx** $\geq$ **nrhs**.

6.   Further Comments

The time taken by the function is approximately proportional to $n^2 r$.

The function may be called with the same actual array supplied for parameters **b** and **x**, in which case the solution vectors will overwrite the right-hand sides.

6.1.   Accuracy

The solutions should be the best possible for the precision of computation having regard to the condition of A. The computed solution x, corresponding to the right-hand side b, satisfies the bound

$$\frac{\|x - A^{-1}b\|}{\|A^{-1}b\|} \leq c\epsilon k.$$

Here c is a modest function of n, ϵ is the **_machine precision_**, and k is the condition number defined by

$$k = \|A\| \, \|A^{-1}\|.$$

6.2.   References

Wilkinson J H and Reinsch C (1971) *Handbook for Automatic Computation (Vol II, Linear Algebra)* Springer-Verlag pp 9–30.

7.   See Also

nag_complex_cholesky (f01bnc)

8.   Example

To solve the set of linear equations $AX = B$ where A is the positive-definite Hermitian matrix:

$$\begin{pmatrix} 15 & 1-2i & 2 & -4+3i \\ 1+2i & 20 & -2+\ i & 3-3i \\ 2 & -2-\ i & 18 & -1+2i \\ -4-3i & 3+3i & -1-2i & 26 \end{pmatrix}$$

and B is the single column vector:

$$\begin{pmatrix} 25+34i \\ 21+19i \\ 12-21i \\ 21-27i \end{pmatrix}.$$

8.1. Program Text

```
/* nag_hermitian_lin_eqn_mult_rhs(f04awc) Example Program
 *
 * Copyright 1990 Numerical Algorithms Group.
 *
 * Mark 1, 1990.
 */

#include <nag.h>
#include <stdio.h>
#include <nag_stdlib.h>
#include <nagf01.h>
#include <nagf04.h>

#define NMAX 8
#define TDA NMAX
#define TDB 2
#define TDX 2
#define COMPLEX(A) A.re, A.im

main()
{
  Integer i, j, n;
  Complex a[NMAX][TDA], b[NMAX][TDB], x[NMAX][TDX];
  double p[NMAX];
  Integer nrhs = 1;
  static NagError fail;

  Vprintf("f04awc Example Program Results\n");
  /* Skip heading in data file */
  Vscanf("%*[^\n]");
  Vscanf("%ld", &n);
  if (n<0 || n>NMAX)
    {
      Vfprintf(stderr,"\nn is out of range: n = %ld\n", n);
      exit(EXIT_FAILURE);
    }
  for (i=0; i<n; ++i)
    for (j=0; j<=i; ++j)
      Vscanf(" ( %lf , %lf ) ", COMPLEX(&a[i][j]));
  for (i=0; i<n; ++i)
    for (j=0; j<nrhs; ++j)
      Vscanf(" ( %lf , %lf ) ", COMPLEX(&b[i][j]));
  /* Factorize A */
  fail.print = TRUE;
  f01bnc(n, (Complex *)a, (Integer)TDA, p, &fail);
  if (fail.code != NE_NOERROR)
    exit(EXIT_FAILURE);
  /* Solve A */
  f04awc(n, nrhs, (Complex *)a, (Integer)TDA, p, (Complex *)b,
         (Integer)TDB, (Complex *)x, (Integer)TDX, &fail);
  if (fail.code != NE_NOERROR)
    exit(EXIT_FAILURE);
  Vprintf("\nSolution\n\n");
  for (i=0; i<n; ++i)
    {
      for (j=0; j<nrhs; ++j)
        Vprintf("  (%7.4f,%7.4f)", COMPLEX(x[i][j]));
      Vprintf("\n");
    }
  exit(EXIT_SUCCESS);
}
```

8.2.   Program Data

```
f04awc Example Program Data
  4
(15.0,  0.0)
( 1.0,  2.0)  (20.0,  0.0)
( 2.0,  0.0)  (-2.0, -1.0)  (18.0,  0.0)
(-4.0, -3.0)  ( 3.0,  3.0)  (-1.0, -2.0)  (26.0,  0.0)
(25.0, 34.0)  (21.0, 19.0)  (12.0,-21.0)  (21.0,-27.0)
```

8.3.   Program Results

```
f04awc Example Program Results

Solution

  ( 1.4917, 2.1788)
  ( 1.1629, 0.7698)
  ( 0.5506,-1.3977)
  ( 0.8691,-0.7655)
```